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First Order Lag Process				
<u>Characterist</u> <u>Examples:</u>	<ul> <li>ics: 1) Single storage element</li> <li>2) Input produces an output related to amount of storage</li> <li>3) Another name: self-regulating process</li> <li>Series R-C circuit</li> <li>Series R-L circuit</li> <li>Self-regulating tank (valve on output)</li> <li>Tank heating</li> </ul>			
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Example 19-1 Solution (4)				
For Laminar flow $R_2 = \frac{128  \mu L}{\pi d^4} P_{\alpha} - 5/m^3$ $L = p_1 p_2   e_{ng} + h_{\alpha} = 0.160  p_{\alpha} - 5$				
$R_{L} = \frac{128(0.160 \text{ P-s})(5m)}{\pi (2.85 \times 10^{2} \text{ m})^{4}}$				
$R_{2} = \frac{102.4}{\pi (6.5975 \times 10^{-7})} = 4.94 \times 10^{-7} Pa - 5/m^{3}$				
Now compute the tank time $\gamma = R_L C_L$ constant $\gamma = (4.94 \times 10^7 \text{ Hz} - 5/\text{ M}^3)(1.425 \times 10^{-9} \text{ M}^3/\text{Ps})$				
Tank level reduced to 63.2% of initial value after 117.3 minutes with $q_{in}=0.99.2\%$ empty after 57. $M = 7040 \text{ s}$ $III7.3 \text{ min}$ $\gamma = 7040 \text{ s}$ $II77.3 \text{ min}$				





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Step Response and Bode Plots of The First- Order Lag Process			
MatLAB Code	<pre>% close all previous figures and clear all variables close all; clear all; % input the integral time constant Tl=input('enter the process time constant: '); G=input('enter the gain of the process: '); % construct and display the system sys=tf(G,[Tl 1]); sys % plot the frequency response bode(sys); % construct a new figure and plot the time response figure; % define a range of time t=(0:500:5*Tl); % use it to generate a step response plot step(sys,t);</pre>		

















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Dead-Time Process						
Characteristic: Energy or mass transported over a distance Common in process industries (Chemicals Refining etc)						
Time domain equation: $f_o(t) = f_i(t - t_d)$ $t_d = \frac{D}{v}$	- t <sub>d</sub> )					
<b>Transfer function:</b> $\frac{F_o(s)}{F_i(s)} = e^{-t_d \cdot s}$	Where: $f_o(t) = output function$ $f_i(t) = input function$ v = velocity of response travel (m/sec) D = distance from input to output $t_d = dead$ -time lag (sec or minutes) $F_o(s) = Laplace transform of output$ $F_i(s) = Laplace transform of input$					









